

**Net Torque** 1.1  $\Sigma \tau = I a_a$

**Avg Acceleration**  $a_{avg} \equiv \frac{v_f - v_i}{t_f - t_i} = \frac{\Delta v_x}{\Delta t}$  or  $a \equiv \frac{F_{net}}{m}$

**Position**  $x_f - x_i = \frac{1}{2} (v_i + v_f) t$

**Velocity**  $v_f = \sqrt{v_i^2 + 2a(x_f - x_i)}$

8.10  $v_f = v_i + at$

8.1:  $a = \frac{v_f - v_i}{t}$

8.2  $t = \frac{v_f - v_i}{a}$

8.3:  $v_i = v_f - at$

**Momentum** 8.3.2  $p = mv \text{ kg} \cdot \text{m} / \text{s}$

**Projectile**

$y_f = h = \frac{v_i^2 \sin^2 \theta_i}{2g}$

$x_f = R = \frac{v_i^2 \sin 2\theta_i}{g}$

**Atwood Machine** 8.3.5  $\Delta F = (m_1 + m_2) a$

$a = \left( \frac{m_2 - m_1}{m_1 + m_2} \right) g$  or  $T = \left( \frac{2m_1 m_2}{m_1 + m_2} \right) g$

**Radian** ( $\theta \approx 57^\circ$ )

8.5  $\theta = 180^\circ \div \pi$

8.6  $\theta = \frac{s}{r}$  where  $s$  = arc length

**Radial Accel** 9.0:  $a_r = \frac{v^2}{r}$

**Angular Accel**  $\alpha_a = \frac{a_T}{r} = \frac{d\omega}{dt}$  in  $\text{rad} / \text{s}^2$

Where  $a_T$  = Linear Tangential acceleration

9.0.2  $a_T = a_r r$

**Period of rotation** 9.1  $t = \frac{2\pi r}{v}$

**Velocity of rotation** 9.2  $v = \frac{2\pi r}{t}$

**Angular Velocity** 9.2.1  $\omega = \text{Angular Velocity } \text{rad/s}$

9.2.2  $\omega = \frac{\Delta \theta}{\Delta t}$

**Tangential Velocity** 9.2.3  $v = r\omega$

**Angular Momentum**  $L = r \times p$

Where  $p$  = Linear Momentum  $L = I\omega$

**Moment of Inertia**  $\text{kg} \cdot \text{m}^2$   $I = \Sigma m_i r_i^2$

Continuous 2D  $I = \int r^2 dm$

Continuous 3D  $I = \int \rho r^2 dV$

**KE of rotat rigid object**  $KE_R = \frac{1}{2} I \omega^2$

**Torque**  $N \cdot m$  9.5  $\tau = r \times F$

9.6  $\tau = \frac{dL}{dt}$

9.7  $\Sigma \tau = I a_a$

**Work - KE for rotation** 9.8  $W = \Delta K_R$

**Power - Rotational**  $P = \frac{dW}{dt} = \tau \frac{d\theta}{dt} = \tau \omega$

**KE of Rolling mass**  $KE_{Rol} = \frac{1}{2} I_{CM} \omega^2 + \frac{1}{2} M v_{CM}^2$

**Falling object if acceleration at height known**

$y_f = y_i + y_{yt} - \frac{1}{2} g t^2$

$t = \sqrt{\frac{y_f - y_i - y_{yt}}{-\frac{1}{2} g}}$

$y_{yt}$  = the initial position at the initial time

$mgh = \frac{1}{2} m v^2$

**Force due to a friction Coefficient**  $F_s = \mu_s N$

where  $\mu_s$  = magnitude of normal force against the surface.  
 $\mu_s N = mg$

**Resistance Due to air**  $R = \frac{1}{2} D \rho A v^2$

$a = g - \left( \frac{D \rho A}{2m} \right) v^2$

$g = \left( \frac{D \rho A}{2m} \right) v_T^2$

$v_T = \sqrt{\frac{2mg}{D \rho A}}$

**DE for finding time taken to reach 90% of Terminal V**

(1) Find coefficient  $b = \frac{mg}{v_T}$

(2) Find Time constant Tau  $\tau = \frac{m}{b}$

(3) Sub (1) & (2) into (3)  $v = v_T (1 - e^{-t/\tau})$

The scalar product of 2 vectors  $\vec{A} \cdot \vec{B} \equiv AB \cos \theta$

**Work Done** 1Nm = 1Joule  $W \equiv F \Delta r \cos \theta$

15.1  $W = FD$

**Work KE theorem** 15.3  $W_{net} = E_{kf} - E_{Ki}$

15.4  $W = \Delta KE$

17.0 **Impulse**  $\text{Im pulse} = FT$

but F is really the change in MOMENTUM  
 $I = (mv_f - mv_i) / t$

17.1  $Ft = \Delta mv$

18.0 **Power**  $P = \frac{\text{Work}}{\text{Time}}$

18.1  $IW (\text{watt}) = 1 \frac{J}{s}$

**Potential Energy** 19.0  $PE = U_p = mgh$

**Kinetic Energy** 20.0  $KE = \frac{1}{2} m v^2$

20.1  $KE = F \times D$

Rotating body 20.2  $KE_k = \frac{1}{2} m v^2 + \frac{1}{2} I \omega^2$

**Equilibrium of a rigid body**  $\Sigma \tau = 0$  &  $\Sigma F = 0$

**SHM**  $x(t) = A \cos(\omega t + \phi)$

$\phi$  = phase constant  
 $\omega$  = angular frequency

**Springs** 22.0  $F = kx$

From pg 375  $\omega^2 = k/m$

$m\omega^2 = k$

$k$  = spring constant in Nm  
 $x$  = compression of spring

**Energy of a simple harmonic oscillator** - 381

$W = \frac{1}{2} k x^2$  or  $E = \frac{1}{2} k A^2$

If there is no displacement at time  $t = 0$

**Phase Constant**  $\phi = \pi / 2$

If displacement  $y = A \sin \phi$

which rearranges to  $\phi = \sin^{-1} y/A$

Angular wave number  $k = 2\pi / \lambda$

**Wave function (sin)**  $y = A \sin(kx - \omega t + \phi)$

**Amplitude**  $A = \sqrt{x_i^2 + \left( \frac{v_i}{\omega} \right)^2}$

**Period of 1 complete oscillation**

$T = \frac{2\pi}{\omega}$   $T = 2\pi \sqrt{(L/g)}$   $g = \left( \frac{L}{2\pi} \right)^2$

**Maximum Transverse wave speed and acceleration**

22.1.2.1  $v_{y,max} = \omega A$

22.1.2.2  $a_{y,max} = \omega^2 A$

**angular frequency (Hz)**  $\omega = 2\pi f = \frac{2\pi}{T}$

**Frequency**  $f = \frac{1}{T} = \frac{\omega}{2\pi} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$

**Position and Acceleration of a particle in Simple Harmonic Motion** pg - 377

$v = \frac{dx}{dt} = -\omega A \sin(\omega t + \phi)$

$v = \frac{d^2x}{dt^2} = -\omega^2 A \cos(\omega t + \phi)$

$v = \sqrt{k(A^2 - x^2)}$

**Position**  $x = A \cos(\omega t + \phi)$

**Velocity**  $v = -\omega A \sin(\omega t + \phi)$

**Acceleration**  $a = -\omega^2 A \cos(\omega t + \phi)$

**PE of a spring**  $PE = U = \frac{1}{2} k x^2$

Find the speed ( $v$ ) of something after being released from the spring  
(Elastic PE in Spring)  $PE_{initial} = KE_{final} (\text{of Mass})$

$\frac{1}{2} k x^2 = \frac{1}{2} m v^2$

rearrange to  $v = \sqrt{\frac{1}{2} \frac{k x^2}{m}}$

to allow for friction  $v = \sqrt{\frac{1}{2} \frac{k x^2 - F_f x}{m}}$

$K$  = sum of all kinetic energies in a system  
 $U$  = Total potential energy in a system

**Pendulums**  $\omega = \sqrt{\frac{g}{L}}$  and  $T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{L}{g}}$

**To find the force in a system from the KE and distance**

23.0  $F_x = -\frac{dU}{dx}$

**Inelastic Collision**  $m_1 v_1 + m_2 v_2 = (m_1 + m_2) v_f$

**Elastic Collisions** - If both masses are the same their angles after collision will be at  $90^\circ$

$U_{1i} + U_{2i} = U_{1f} + U_{2f}$

**Power -**  $P = \frac{dE}{dt}$

$\frac{\text{Energy} = \text{Power} \times \text{Time}}{\text{Measured in Watts}}$

$U_g = \text{gravitational PE} = E_p = mgh$

$U_{mech} = E_{KE} + E_{PE} = K + U_g$

$KE^{pot(ox)} + bE^{pot(ox)} = KE^{kin(ox)} + bE^{kin(ox)}$

$mgh = \frac{1}{2} m v^2$

rearranges to  $v_f = \sqrt{2gh}$

**Pressure**  $P = F / A$

**Pressure**  $P = P_0 + \rho gh$  where  $\rho = \text{density}$

or  $\rho = \frac{m}{V} = \frac{\text{mass}}{\text{Volume}}$

$1 Pa = 1 N / m^2 = 1 atm$

**Centre o Mass**  $x_{cm} = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$

**Static Friction**  $f_s = \mu_s n$

where  $n$  = Opposing force to  $mg$

$\mu_s$  = Coefficient of Static friction

**Buoyancy** The weight of the liquid displaced is equivalent to the weight of the object  
 $B = P_{bot} A - P_{top} A = \Delta P A = \rho_f g h A$

where  $V = hA$  &  $M = \rho_f V$

$B = \rho_f g V$

**Inertial Moments**

Cylindrical Shell  $I = MR^2$

Hollow Cylinder  $I = 1/2 MR^2 (R_1^2 + R_2^2)$

Solid Cylinder  $I = 1/2 MR^2$

Rectangular Plate  $I = 1/12 M (a^2 + b^2)$

Long rod centre axis  $I = 1/12 ML^2$

Long rod end axis  $I = 1/3 ML^2$

Solid Sphere  $I = 2/5 MR^2$

Thin spherical shell  $I = 2/3 MR^2$

**Universal Gravity**  $F_g = G \frac{m_1 m_2}{r^2} = m \frac{v^2}{r}$

**Velocity of Satellite of Earth** 35.1  $v = \sqrt{\frac{GM_E}{r}}$

**Grav Constant**  $G = 6.673 \times 10^{-11} N \cdot m^2 / kg^2$

**Gravitational Field** pg-339 37.0  $g = G \frac{F_g}{m}$

**Kepler's 3<sup>rd</sup> Law**  $T^2 = \left( \frac{4\pi^2}{GM_s} \right) a^3 = K_s a^3$

**ME of planet Star system** 39.0  $E = -\frac{G M m}{2a}$

Where  $a$  is the radius or the semi major axis

**Escape Speed**  $v_{esc} = \sqrt{\frac{2GM}{R}}$  where  $R$ =Radius

**Acceleration in an ElecField**  $a = \frac{qE}{m}$

**Elec Field due to a finite # of point charges**  $E = k \Sigma \frac{q_i}{r^2} \hat{r}$

**Elec Field of a continuous charge distribution**  $E = k \int \frac{dq_i}{r^2} \hat{r}$

**Resistors in Parallel**  $R_{eq} = \frac{1}{\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3}}$

**Change in PE for a Charge Field System**  $\Delta U = U_B - U_A = -q_0 \int_A^B E \cdot ds$

Where 's' = displacement.

**Electric Potential**  $V = \frac{U}{q_0}$

**Potential Difference between 2 points In an electricfield**  $V = \frac{U}{q_0} = -\int_A^B E \cdot ds$

**Potential Difference** p645  $\Delta V = -E \Delta d$

**PE Difference**  $\Delta U = q \Delta V = W$

**Equipotential Surfaces**  $V = k \frac{q}{r}$

**Capacitance** p-657  $C = \frac{Q}{V}$  in Farads  $IF=ICV$

**Charge per unit area**  $\sigma = \frac{Q}{A}$  Where  $Q$  = charge

**E between Capacitor plates**  $E = \frac{V_B - V_A}{d}$

**V Between Plates**  $V = Ed$

**Capacitor** p-671  $C = k \frac{\epsilon_0 A}{d}$

**Electric potential energy of a pair of point charges** p673  $U = k \frac{q_1 q_2}{r_{12}}$

53.0  $U = k \frac{q_1 q_2}{r_{12}}$

**Energy stored in a charged capacitor** p665  $U = k \frac{Q^2}{2C} = \frac{1}{2} Q \Delta V = \frac{1}{2} C (\Delta V)^2$

**C in Parallel**  $C_{eq} = C_1 + C_2 + C_3 + \dots$

**Capacitance Series**  $C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$

**Capacitance with a dielectric** 54.3  $C = kC$

**Charging a C**  $\tau = RC$

$q(t) = Q_{max} (1 - e^{-t/RC})$

$I(t) = I_{initial} e^{-t/RC} = \frac{\mathcal{E}}{R} e^{-t/RC}$

**Discharging a C**  $q(t) = Q_{max} e^{-t/RC}$

$I(t) = -I_{initial} e^{-t/RC}$

**Fluid Continuity**  $A_1 v_1 = A_2 v_2$

**Bernoulli's theorem**  $P_1 + \frac{1}{2} \rho v_1^2 + \rho g y_1 = P_2 + \frac{1}{2} \rho v_2^2 + \rho g y_2$

**Coulomb's Law** p608  $F = k \frac{q_1 q_2}{r^2}$

- p634 vector form  $F_{12} = k \frac{q_1 q_2}{r^2} \hat{r}_{12}$

**Definition of elec field**  $E = F / q$  unit N/C

**Elec Field due to point charge**  $E = k \frac{q_1}{r^2} \hat{r}$

$E$  = Electrical field  
 $q_1$  = charge

**Electric Current**  $I = \frac{dQ}{dt} = nA \Delta x q$

$IA = IC/s$   
 $\Delta x$  = drift Velocity

Where  $\lambda = \frac{v}{f} = vT = \frac{2\pi}{k}$

**Mass per unit length**  $\mu = m / \ell$

**EMF** pg 699 54.5  $\Delta V = \mathcal{E} - Ir$

54.6  $IR = \mathcal{E} - Ir$

**Power - P35** 55.3  $P = i^2 R$

55.4  $P = v^2 / R$

55.5  $P = Vi$

**Components in a circuit will add to zero**  $P_1 + P_2 + P_3 = 0$

**Resistivity** 56.5  $R = \frac{\rho L}{A}$

Variation with temp  $R = R_0 [1 + \alpha(T - T_0)]$

**Magnetic Fields**

$B$  = Magnetic Force in Teslas (T)  
 $F = qvB \sin \theta$

**Radius of path of electron or proton n a magnetic field**

Pg 733 56.9  $r = \frac{mv}{qB}$

**Angular Particle speed** (cyclotron frequency) 57.0  $\omega = \frac{v}{r} = \frac{qB}{m}$

**Particle Period**  

$$T = \frac{2\pi r}{v} = \frac{2\pi}{\omega} = \frac{2\pi \cdot m}{qB}$$

**Lorentz Force** – particle acted on by magnetic and elec forces – p735  

$$F = qE + qv \times B$$

**Mass to charge ratio used in Mass Spectrometer**  

$$57.3 \quad \frac{m}{q} = \frac{rB_0 B}{E}$$

**Doppler Effect** p – 419  

$$f' = f \left( \frac{v + v_o}{v + v_s} \right)$$

**Fundamental Frequency of a stretched string** – pg 441  

$$58.0 \quad f = \frac{1}{2L} \sqrt{\frac{T}{\mu}}$$

**Pulse Velocity on a string** 58.1  

$$v = \sqrt{\frac{T}{\mu}}$$

**Fundamental Frequency in a closed end tube** pg444  

$$59.0 \quad f = \frac{nv}{4L}$$
 where n is the odd harmonic

v = velocity of air L = Tube length F = is the harmonic freq  
 Rearranged to  

$$L = \frac{nv}{f4}$$

**Gravitational Force** 60.0  

$$F = G \frac{m_1 m_2}{d^2}$$

**Radius of a geostationary satellite**  

$$r = \frac{d^2 v^2}{Gm_2}$$

**Beat Frequency**  

$$f_b = [f_1 - f_2]$$

**Average Frequency**  

$$f_{avg} = [f_1 + f_2]/2$$

Gig	<b>G</b>	10 <sup>9</sup>
Mega	<b>M</b>	10 <sup>6</sup>
Kilo	<b>k</b>	10 <sup>3</sup>
Milli	<b>m</b>	10 <sup>-3</sup>
Micro	<b>μ</b>	10 <sup>-6</sup>
Nano	<b>n</b>	10 <sup>-9</sup>
Pico	<b>p</b>	10 <sup>-12</sup>
Femto	<b>f</b>	10 <sup>-15</sup>

**Volume Charge Density**  

$$\rho = \frac{Q}{V} \text{ C/m}^3$$

**Surface Charge Density**  

$$\sigma = \frac{Q}{A} \text{ C/m}^2$$

**Linear Charge Density**  

$$\lambda = \frac{Q}{\ell} \text{ C/m}$$

Murdoch University – ENG125 – Gareth Lee

Relation	Resistor	Capacitor (C)	Inductor
v-i:	(R) $v = iR$	$v = \frac{1}{C} \int i dt + v(t_0)$	(L) $v = L \frac{di}{dt}$
i-v:	$i = \frac{v}{R}$	$i = C \frac{dv}{dt}$	$i = \frac{1}{L} \int v dt + i(t_0)$
p or w:	$p = i^2 R = \frac{v^2}{R}$	$w = \frac{1}{2} C v^2$	$w = \frac{1}{2} L i^2$
Series:	$R_{eq} = R_1 + R_2$	$C_{eq} = \frac{C_1 C_2}{C_1 + C_2}$	$L_{eq} = L_1 + L_2$
Parallel:	$R_{eq} = \frac{R_1 R_2}{R_1 + R_2}$	$C_{eq} = C_1 + C_2$	$L_{eq} = \frac{L_1 L_2}{L_1 + L_2}$
At dc:	Same	Open circuit	Short circuit
Circuit var that cannot change	n/a	v	i

**General Figures**  
 mass of an electron pg - 7  $9.11 \times 10^{-31}$   
 mass of proton pg609

charge / mass electron, proton neutron pg 609

**Electron or Proton Charge**  

$$1.6021765 \times 10^{-19}$$
  

$$-1.6021765 \times 10^{-19}$$

**Gravitational Constant**  

$$1 \text{ Volt} = 1 \text{ J/C}$$
  

$$6.67 \times 10^{-11} \text{ N} \cdot \text{m}^2 / \text{kg}^2$$

**CoulombsConstant**  

$$k = 8.99 \times 10^9 \text{ N} \cdot \text{m}^2 / \text{C}^2$$
  

$$k = \frac{1}{4\pi\epsilon_0}$$

**Permittivity**  
 F.S.  

$$8.8542 \times 10^{-12} \text{ C}^2 / \text{N} \cdot \text{m}^2$$

**Speed of electron in a TV tube** is  $8.0 \times 10^6$  m/s. Coil of wire around tube creates a magnetic field of 0.025T at an angle of 60degrees to the x-axis as shown. What is  
**a)The force on the electron**  
 $F = qvB \sin \theta$   
 $F = (1.60 \times 10^{-19})(8.0 \times 10^6)(0.025 \sin 60^\circ)$   
 $F = 2.8 \times 10^{-14} \text{ N down}$   
**b)The acceleration of the electron**  
 $F = ma$   
 $a = 2.8 \times 10^{-14} / 9.1 \times 10^{-31}$   
 $a = 3.1 \times 10^{16} \text{ m/s}^2$

$$1.67262 \times 10^{-27}$$